Integrated Serial LCD Module (ILM-216)

The ILM-216 combines an LCD and microcontroller into a compact module for user-interface applications.

- A 2-line by 16-character LCD with supertwist (high-contrast) screen
- Bidirectional serial interface, 1200 to 9600 baud
- Simple receive-terminal emulation
- Inputs for four pushbuttons or switches that may be read serially
- Output for piezo buzzer activated by ASCII bell character
- Nonvolatile EEPROM memory for configuration, special characters, startup screen
- Software control of LED backlight (on backlit models)

The ILM-216’s microcontroller is a PIC16F84, a flash-memory device that can be reprogrammed in circuit. Sophisticated users can reprogram the module to their own specifications. This manual covers only the standard firmware shipped with the ILM-216.

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- Note: Abusing the module, connecting reversed power, or attempting to repair or modify it, voids this warranty.

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Pinout of the ILM-216

Connections to the ILM-216 are made through a row of solder pads located at the bottom edge of the module (figure 1). Table 1 lists the pads' functions.

![Figure 1. Location of pins and contrast control.](image)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>GND</td>
<td>Do not reverse power!</td>
</tr>
<tr>
<td>2</td>
<td>+5V</td>
<td>Do not reverse power!</td>
</tr>
<tr>
<td>3</td>
<td>Serial In</td>
<td>RS-232 or 5-volt logic</td>
</tr>
<tr>
<td>4</td>
<td>Serial Out</td>
<td>5-volt logic level, inverted</td>
</tr>
<tr>
<td>5</td>
<td>Bell Out</td>
<td>25 mA max.</td>
</tr>
<tr>
<td>6</td>
<td>GND</td>
<td>Ground for pins 7 and/or 8</td>
</tr>
<tr>
<td>7</td>
<td>Config/Test</td>
<td>Ground to configure</td>
</tr>
<tr>
<td>8</td>
<td>Force 9600</td>
<td>Ground to force 9600 bps</td>
</tr>
<tr>
<td>9</td>
<td>S1a</td>
<td>Switch input S1</td>
</tr>
<tr>
<td>10</td>
<td>S1b</td>
<td>GND</td>
</tr>
<tr>
<td>11</td>
<td>S2a</td>
<td>Switch input S2</td>
</tr>
<tr>
<td>12</td>
<td>S2b</td>
<td>GND</td>
</tr>
<tr>
<td>13</td>
<td>S3a</td>
<td>Switch input S3</td>
</tr>
<tr>
<td>14</td>
<td>S3b</td>
<td>GND</td>
</tr>
</tbody>
</table>

Do not reverse +5V and GND, even momentarily. Reversed power will destroy the electronics. Do not exceed 5.5V into +5V. Overvoltage will damage the module or shorten its life.

Quick Checkout and Contrast Adjustment

Refer to figure 1. Temporarily connect pins 6 and 7 together. Apply power to pins 1 and 2, ensuring proper polarity as indicated in table 1. When power is applied, the LCD will display the firmware version and factory-configured baud rate, as shown in figure 1. (Actual text may vary.) The LCD contrast is set at the factory. You may adjust it by turning the contrast control with a small, flat-blade screwdriver.

The baud rate shown on the test screen (2400 bps is the factory setting) indicates the baud rate stored in the ILM-216's configuration memory. This is the serial data rate the module will use in normal operation (unless overridden by grounding pin 8). See “Configuration EEPROM.”

**NOTE:** When you are done with checkout, disconnect power and remove the connection between pins 6 and 7. This connection is for test and configuration and must be removed for normal operation.

Hookup for Use

Figure 2 shows how to connect serial I/O and accessories to the ILM-216. You may operate the module without any or all accessories—just leave the unused pins disconnected. Many applications will require just power and serial input.
Basic Operation

Connect serial input and power to the ILM-216 as shown in the previous sections. Make sure that pins 6 and 7 are not connected together (configuration/test mode). If they are, remove power, disconnect pins 6 and 7, and restore power.

Now you can send text serially to the display. On a PC, you may use a terminal program (such as Hyperterminal, included with Windows 95 and later). Set it for the appropriate baud rate (the one you saw on the config/test screen; 2400 is the factory default). To override that baud rate and run at 9600 baud, connect pin 8 to pin 6 as shown in figure 2 above. In addition to the baud rate, the terminal should be set for:

- no parity
- 8 data bits
- 1 stop bit
- flow control = none
- local echo = on

Control Codes and Special Features

Table 2 lists the ILM-216 control codes. To send control codes from a terminal program, hold down Control and press another key. For example, to send ctrl-E (underline cursor) hold down Control and press E. To send control codes from a program, send the ASCII value as a single byte (not as a text representation of the number). Using ctrl-E as an example, send a single byte containing the value 5 (00000101 binary). Control codes not listed in the table are ignored by the ILM-216 and have no effect.
Table 2. Display Control Codes

<table>
<thead>
<tr>
<th>Function</th>
<th>Code</th>
<th>ASCII</th>
</tr>
</thead>
<tbody>
<tr>
<td>Null (ignored prior to buffer)</td>
<td>ctrl-@</td>
<td>0</td>
</tr>
<tr>
<td>Cursor home</td>
<td>ctrl-A</td>
<td>1</td>
</tr>
<tr>
<td>Hide cursor</td>
<td>ctrl-D</td>
<td>4</td>
</tr>
<tr>
<td>Show underline cursor</td>
<td>ctrl-E</td>
<td>5</td>
</tr>
<tr>
<td>Show blinking-block cursor</td>
<td>ctrl-F</td>
<td>6</td>
</tr>
<tr>
<td>Bell (pulse piezo-buzzer output)</td>
<td>ctrl-G</td>
<td>7</td>
</tr>
<tr>
<td>Backspace*</td>
<td>ctrl-H</td>
<td>8</td>
</tr>
<tr>
<td>Horizontal tab (cursor to next multiple-of-4 column)*</td>
<td>ctrl-I</td>
<td>9</td>
</tr>
<tr>
<td>Smart linefeed (cursor down one line)</td>
<td>ctrl-J</td>
<td>10</td>
</tr>
<tr>
<td>Vertical tab (cursor up one line)</td>
<td>ctrl-K</td>
<td>11</td>
</tr>
<tr>
<td>Formfeed (clear screen)</td>
<td>ctrl-L</td>
<td>12</td>
</tr>
<tr>
<td>Carriage return*</td>
<td>ctrl-M</td>
<td>13</td>
</tr>
<tr>
<td>Backlight on</td>
<td>ctrl-N</td>
<td>14</td>
</tr>
<tr>
<td>Backlight off</td>
<td>ctrl-O</td>
<td>15</td>
</tr>
<tr>
<td>Accept cursor-position entry</td>
<td>ctrl-P</td>
<td>16</td>
</tr>
<tr>
<td>Format right-aligned text</td>
<td>ctrl-R</td>
<td>18</td>
</tr>
<tr>
<td>Escape (ESC; start multipart instruction)</td>
<td>ctrl-[</td>
<td>27</td>
</tr>
</tbody>
</table>

- Define graphics character: \( ESC \ D \ n \ B0 \ B1 \ B2 \ B3 \ B4 \ B5 \ B6 \ B7 \)
  where \( n \) is the character number (0—7) and B0—B7 are bytes mapping the pixels

- Transfer data from EEPROM to display: \( ESC \ E \ n \)
  where \( n \) is “0” or “1” with 0 meaning text screen and 1 meaning symbols

- Read the keys \( (S1—S4) \) and report serially: \( ESC \ K \ n \)
  where \( n \) sets format—0 = single byte, bits 0—3 correspond to S1—S4 and
  1= four bytes consisting of text characters “0” and “1” (a “1” means switch closed)

**Null** (control-@, ASCII 0)

Nulls are ignored; sending a null to the display has no effect. However, unlike other unused codes, nulls are not even stored in the display buffer. They may be used as a brief time delay whose length depends on the baud rate: 1200 bps = 8.33 ms delay; 2400 bps = 4.16 ms; 4800 bps = 2.08 ms; 9600 bps = 1.04 ms.

**Cursor Home** (control-A, ASCII 1)

Move the cursor to the first character position of the first line.

**Hide Cursor** (control-D, ASCII 4)

Hide the cursor (either type, blinking or underline).

**Show Underline Cursor** (control-E, ASCII 5)

Show a non-blinking underline cursor at the printing location.

**Show Blinking-Block Cursor** (control-F, ASCII 6)

Show a blinking block cursor at the printing location.

**Bell** (control-G, ASCII 7)

Pulse pin 5 low for approximately 100 ms to beep piezo buzzer.

**Backspace** (control-H or backspace key, ASCII 8)

Move the cursor back one space and erase the character in that space.

**Horizontal Tab** (control-I or Tab key, ASCII 9)

Move the cursor forward to next multiple-of-four column.

**Smart Linefeed** (control-J, ASCII 10)

Move cursor down one line. If immediately preceded by carriage return, linefeed is ignored.

**Vertical Tab** (control-K, ASCII 11)

Move cursor up one line.
Clear Screen (control-L, ASCII 12)
Clear the screen.

Carriage Return (control-M, ASCII 13)
Move cursor to the first position of the next line.

Backlight ON (control-N, ASCII 14)
Turn on the LED backlight. Current draw is approximately 40 mA.

Backlight OFF (control-O, ASCII 15)
Turn off the LED backlight.

Position Cursor (control-P, ASCII 16)
Accept a number from 0 to 31 and move the cursor to that screen position (where 0 is the first character of the first line and 31 is the last character of the second line). Number may be in text or single-byte format:
  - Text method: Send the desired display position as printable text. For example, to move the cursor to position 21 (6th character, 2nd line) from a terminal program, press control-P, and type “21” followed by a space or other character (which will be discarded).
  - One-byte method: Send a single byte whose value is 64 + position. For example, to move to position 21, send a control-P (ASCII 16) followed by a byte value of 85 (64 + 21).

Right-align Text (control-R, ASCII 18)
Accept a number from 2 to 9 (as text) representing the width of an area on the screen in which right-aligned text is to be printed. Cursor will back up that number of characters from present cursor position. Subsequent text will be stored without printing to the screen until one of the following is received:
  - The specified number of characters.
  - A control character (ASCII 1–31).
  - A decimal point (the period (.) character, ASCII 46).
The display will print the text with right alignment and erase any leftover text within the specified width. For example, move the cursor to the right end of the screen, send control-R (ASCII 18), followed by “5” (ASCII 53), then “123” and Enter. The “123” will be printed right-aligned within the 5-character space.

Escape Sequences (control-, ASCII 27, followed by additional instructions)
The ILM-216 understands three instructions that begin with the escape code (ASCII 27).

• Define a Custom Character (ESC D n B0 B1 B2 B3 B4 B5 B6 B7)
The ILM-216 has eight custom-character slots. These characters are mapped to ASCII codes 128 through 134. At startup, the unit loads bitmaps into the first six custom characters from its EEPROM. Using the Define instruction, you can change a bitmap. Send Escape (ASCII 27) followed by the letter D (ASCII 68), then the symbol number you wish to define (0—7, ASCII 48—55), followed by eight bytes defining the bitmap. The contents of those bytes map to the custom symbol as shown in figure 4.

• Transfer Data from EEPROM (ESC E n)
The ILM-216 has 64 bytes of EEPROM, which may be used to store configuration data, such as text for a startup screen or default patterns for the first six custom characters (ASCII 128 through 133). Using the EEPROM instruction, you can transfer that data from EEPROM to the display. Send Escape (ASCII 27), followed by the letter E (ASCII 69), then the number 0 or 1 (ASCII 48 or 49) to perform a transfer. ESC E 0 causes the EEPROM text screen to be displayed. ESC E 1 reloads the first six custom characters from EEPROM. Since those custom characters are automatically loaded at startup, the only time you might use ESC E 1 is to undo changes made by a previous definition of custom characters (ESC D n...).
• **Read the Keys (ESC K n)**

The ILM has four inputs that may be used to read a four-button keypad (S1—S4). The Key instruction returns the states of those switches via the serial output. Send Escape (ASCII 27) followed by K (ASCII 75), then the number 0 or 1 (ASCII 48 or 49). ESC K 0 returns a single byte whose lower four bits correspond to the states of the keys (where 0 means open and 1 means closed). S1 corresponds to bit 0, S2 to bit 1 and so on. The upper four bits will always be 0100 binary. If you send ESC K 0 from a terminal, you will see the returned byte as a single character: @ (no keys pressed), or A through O (one or more keys pressed).

ESC K 1 returns four bytes consisting of 0 (ASCII 48) for open switches and 1 (ASCII 49) for closed switches. From a terminal, you would see “0100” assuming that S2 was closed and the others open.

**Configuration EEPROM**

The ILM-216 stores settings, custom characters, and a 32-character text screen in 64 bytes of EEPROM. This kind of memory retains its contents without power. Table 3 shows the format of the EEPROM configuration. Configuration software is available from www.seetron.com.

To download data to the EEPROM, connect the ILM-216 to a PC as shown in figure 3. Temporarily connect pins 6 and 7 of the ILM-216 together, and power the unit. It will display the screen shown in figure 1 (with some possible variations in the text). The ILM-216 is waiting to receive 64 bytes that it will copy to EEPROM. The download baud rate is fixed at 2400 bps. Select the desired settings in the configuration software and press Download (Windows version; see readme file accompanying DOS version). When the download is over, the screen will display “Setup Complete.” To use the ILM-216, turn off power and disconnect pins 6 and 7.

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### Table 3. Configuration Bytes

<table>
<thead>
<tr>
<th>Byte No.</th>
<th>Function</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>0—29</td>
<td>Custom symbols</td>
<td>Each of 6 symbols is defined by 8 rows of 5 bits, for a total of 240 bits packed into 30 bytes. For example config byte 0 contains symbol 0, row 0, bits 0—4 and symbol 0, row 1, bits 0—2.</td>
</tr>
<tr>
<td>30</td>
<td>Settings,</td>
<td>Bits 1 and 0 set the baud rate: 00 = 9600, 01 = 4800, 10 = 2400, 11 = 1200</td>
</tr>
<tr>
<td></td>
<td>Power-on delay</td>
<td>Bit 2 determines backlight status at startup: 0 = OFF, 1 = ON</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 3 determines screen status at startup: 0 = blank, 1 = EEPROM text (bytes 32—63)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bits 4 through 7 form a four-bit value (0—15) that sets a startup delay in units of 2.5 seconds (0 to 37.5 seconds). After power is applied, the ILM-216 ignores its serial input for the startup-delay time (firmware v28 and higher).</td>
</tr>
<tr>
<td>31</td>
<td>Key delay</td>
<td>Bits 0—3 form a four-bit value (0—15) that sets the delay (in 0.5-ms units) before response to an ESC K keypad query. (Delay lets slow computers prepare for serial receive.) Bits 4—7 are unused.</td>
</tr>
<tr>
<td>32—63</td>
<td>Screen text</td>
<td>A 32-byte string that is written to the screen at startup (if bit 3 of byte 30 above is 1), or whenever an ESC E 1 instruction is received.</td>
</tr>
</tbody>
</table>

**Factory Settings.** The ILM-216 ships with default settings loaded into its EEPROM. The custom characters are as shown in figure 5; the default baud rate is 2400 bps (which may be changed to 9600 by shorting pin 8 to pin 6 or other GND); at startup the backlight is off and the screen is blank; the delay after an ESC K key read is set to 2.5 ms; startup delay is 0; and the screen text (displayable by ESC E 0) is set to “Scott Edwards Electronics Inc.” or custom text requested by a distributor.
Program Examples

Any computer/programming language that can produce serial output (1200 to 9600 bps, N81) can talk to the ILM-216. The examples here are in BASIC, chosen because of its popularity and readability. (A C programmer can readily understand BASIC, but a BASIC programmer generally cannot read C.)

These examples are meant to illustrate only the fundamentals. More examples are available from www.seetron.com.

' BASIC STAMP I
' Assumes ILM-216 set for 2400 bps (factory default), serial in (pin 3) connected
to BS1 pin 0. Uses ctrl-P (position, ASCII 16) and ctrl-L (clear screen, ASCII 12)
PAUSE 1000         ' Wait for display to initialize.
SEROUT 0,N2400,(12,"Hello World!")         ' Clear screen, show message.
PAUSE 2000     ' Wait 2 secs, go to line 2, character 5 (position 21--
SEROUT 0,N2400,(16,85,"line 2")     ' ..64 + 21 = 85).and print.
PAUSE 2000: SEROUT 0,N2400,(12, "Goodbye.")     ' Wait 2 seconds, clear screen, say bye.

' BASIC STAMP II
' Assumes ILM-216 set for 2400 bps (factory default), serial in (pin 3) connected
to BS2 pin P0. Uses ctrl-P (position, ASCII 16) and ctrl-L (clear screen, ASCII 12)
' If ILM-216 is set for 9600 bps, use $4054 ($40F0 for BS2-SX) as Serout baudmode.
N2400 con $418D       ' Define inverted, 2400-bps serial ($43FD for BS2-SX)
PAUSE 1000         ' Wait for display to initialize.
SEROUT 0,N2400,[12,"Hello World!"]         ' Clear screen, show message.
PAUSE 2000     ' Wait 2 seconds, then go to line 2 (position 16--
SEROUT 0,N2400,[16,85,"line 2..."]     ' ..64 + 21 = 85) and print.
PAUSE 2000:SEROUT 0,N2400,[12,"Goodbye."]     ' Wait 2 secs, clear screen, say bye.
Program Examples (cont.)

' QBASIC, QuickBASIC, PowerBASIC (including First BASIC) for PCs under DOS
' Note: QBASIC is the BASIC interpreter that Microsoft shipped with most versions of
' DOS. An alternative is PowerBASIC or First BASIC, from www.powerbasic.com (or go
' to www.seetron.com and follow the link from the ILM-216 support page).
' Program assumes ILM-216 set for 2400 bps (factory default), connected
' as shown in figure 3. If you are using a serial port other than com1,
' modify the OPEN instruction accordingly. Program uses ctrl-P (position,
' ASCII 16) and ctrl-L (clear screen, ASCII 12).

OPEN "COM1:2400,N,8,1,CD0,CS0,DS0" FOR OUTPUT AS #1  ' Open the serial port.
PRINT #1, CHR$(12);"Hello World"; ' Clear screen, show message.
' Now move to the middle of line 2 (position 21; 64 + 21 = 85) and print.
PRINT #1, CHR$(16);CHR$(85);"Line 2";  ' Print in middle of line 2.
INPUT "Press Enter",X$  ' Wait for a key press.
PRINT #1,CHR$(12);"Goodbye.";  ' Clear screen, say bye.

Dimensions and Specifications

Additional information not covered by this manual (schematic, more program examples, configuration
downloading utility, developer program, etc.) may be obtained from www.seetron.com. You may also
request hardcopy by mail.

Table 4. Basic Specifications

<table>
<thead>
<tr>
<th>Dim.</th>
<th>Power requirements .............4.8 to 5.5 Vdc @ 5 mA (40 mA, backlit)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>User connector ....................................................................</td>
</tr>
<tr>
<td></td>
<td>Connector pinout ..................................................................</td>
</tr>
<tr>
<td></td>
<td>Serial input ............................................RS-232, or inverted TTL/CMOS, 1200—9600, N81</td>
</tr>
<tr>
<td></td>
<td>Serial output ...........................................inverted TTL; 0-5V, 1=0V (not true RS-232)</td>
</tr>
<tr>
<td></td>
<td>Buffer depth ......................................................................16 bytes</td>
</tr>
<tr>
<td></td>
<td>Operating temperature .................................................0° to 50°C (32° to 122°F)</td>
</tr>
<tr>
<td></td>
<td>Storage temperature .................................................-10° to 60°C (14° to 140°F)</td>
</tr>
<tr>
<td></td>
<td>LCD type .........................................................................Supertwist (STN), yellow-green</td>
</tr>
<tr>
<td></td>
<td>Optimum viewing direction .............................................6 o'clock</td>
</tr>
</tbody>
</table>

Figure 6. Physical dimensions

All dimensions in mm.
* Worst-case tolerance for any dimension is ±0.50mm.
* Maximum depth (from front of screen frame to highest point on pcb) is 15mm